

## Writedata\_ols.c

```
/* writedata_ols.c -- Writes out a file for ols_read.c. The X matrix
 * is random data, the BETA vector is pre-set, and Y vector is X*BETA.
 * The first column is Y, the second is a column of "1"s for the
 * intercept, and the remaining columns are drawn from the rand()
 * function. User sets number of columns and number of rows below. */
#include <stdlib.h>
#include <stdio.h>
/* Declare pointer to the output file */
FILE *kp;

int main(void){

    int nrow=1000, ncol=25;
    double *X, *Y, *BETA;
    double sum;
    int i = 0;
    int j = 0;

    X = (double *) malloc (nrow*ncol*sizeof(double));
    Y = (double *) malloc (nrow*sizeof(double));
    BETA = (double *) malloc (nrow*sizeof(double));

    /* Open the output file */
    kp = fopen("data_ols.txt","w");

    printf("\nnumber of rows = %d  number of columns = %d\n\n",nrow,ncol);

    /* Initialize BETA vector -- Note that the Constant term will be
     * affected by the means of the variables when OLS.c is run */
    for(j=0;j<ncol;j++)
    {
        BETA[j] = 1;
    }

    srand(14);
    /* Fill X matrix with random numbers*/
    for(i=0;i<nrow*ncol;i++){
        X[i] = ( (double)rand() / ((double)(RAND_MAX)+(double)(1)));
    }
    /* Put "1"s in first Column of X -- Columns are stacked in vector X */
    for(i=0;i<nrow;i++)
    {
        X[i] = 1;
    }
    /* Calculate Y */
    for(i=0;i<nrow;i++)
    {
        sum=0.0;
        for(j=0;j<ncol;j++)
        {
            sum=sum+BETA[j]*X[i+j*nrow];
        }
        Y[i]=sum;
    }
}
```

```

    }

/* For loops for writing out Y and X */
for(i=0;i<nrow;i++)
{
    fprintf(kp, "%7.3f",Y[i]);
    for(j=0;j<ncol;j++)
    {
        fprintf(kp, "%7.3f",X[i+j*nrow]);
    }
/* This is the line feed -- newline at the end of the the jth row */
    fprintf(kp,"\n");
}
fclose(kp);
free(X);
free(Y);
free(BETA);
return(0);
}

```

## ols\_read.c

```
/*
c:/mingw/bin/gcc -I"c:/program files/R/R-2.9.0/include" -L"C:/Program
Files/R/R-2.9.0/bin" -Wall %1.c -o %1.exe -lRlapack -lRblas

General OLS program.  Reads matrix created by writedata_ols.c

The only parameters the user has to set are the number of rows and
columns -- nrow and ncol below.  The number of columns counts a column
of "1"s used for the intercept term.  All memory is then dynamically
allocated using nrow and ncol.
*/
#include <stdlib.h>
#include <stdio.h>
#include <string.h>
#include <R_ext/Lapack.h>
#include <R_ext/BLAS.h>
FILE *fp;

int main(){

    int i, j, info, errno;
    char trans = 't', notrans = 'n';
    double alpha = 1.0, beta=0.0;
    int nrow=1000, ncol=25;
    int one=1;
    double *X, *Y, *XprimeX, *XXinv, *XXinvX, *coef;
    int *ipiv;

    X = (double *) malloc (nrow*ncol*sizeof(double));
    Y = (double *) malloc (nrow*sizeof(double));
    XprimeX = (double *) malloc (ncol*ncol*sizeof(double));
    XXinv = (double *) malloc (ncol*ncol*sizeof(double));
    XXinvX = (double *) malloc (nrow*ncol*sizeof(double));
    coef = (double *) malloc (ncol*sizeof(double));
    ipiv = (int *) malloc (ncol*sizeof(int));

    printf("\nnumber of rows = %d  number of columns = %d\n\n",nrow,ncol);

    if((fp = fopen("c:/docs_c_summer_course/data_ols.txt","r"))==NULL)
    {
        printf("\nUnable to open file OLS_DATA.TXT: %s\n",
strerror(errno));
        exit(EXIT_FAILURE);
    }
    else {

        printf(" Y and X = \n");
        for(i=0;i<nrow;i++)
        {
            fscanf(fp,"%lf",&Y[i]);
            for(j=0;j<ncol;j++)
            {
                fscanf(fp,"%lf",&X[i+j*nrow]);
            }
        }
    }
}
```

```

        }
        printf("%10d %12.6f", i,Y[i]);
        for(j=0;j<ncol;j++)
        {
            printf("%12.6f",X[i+j*nrow]);
        }
        printf("\n");
    }
}

dgemm_(&trans,&notrans,&ncol,&ncol,&nrow,&alpha,X,&nrow,X,&nrow,&beta,
XprimeX,&ncol);
printf("\n\nX'X = \n");
for(i=0;i<ncol;i++)
{
    for(j=0;j<ncol;j++)
    {
        printf("%12.6f",XprimeX[i+j*ncol]);
    }
    printf("\n");
}
/* Initialize the Identity matrix */
for(i=0;i<ncol;i++)
{
    for(j=0;j<ncol;j++)
    {
        XXinv[i+j*ncol]=0.0;
        if(i == j)XXinv[i+j*ncol]=1.0;
    }
}
dgesv_(&ncol,&ncol,XprimeX,&ncol,ipiv,XXinv,&ncol,&info);
printf("\n\n(X'X)-1 = \n");
for(i=0;i<ncol;i++)
{
    for(j=0;j<ncol;j++)
    {
        printf("%12.6f",XXinv[i+j*ncol]);
    }
    printf("\n");
}

//XXinv is 2x2
//X' is 2x5
//X is 5x2

dgemm_(&notrans,&trans,&ncol,&nrow,&ncol,&alpha,XXinv,&ncol,X,&nrow,&b
eta,XXinvX,&ncol);

//XXinvX is 2x5
//Y is 5x1

dgemm_(&notrans,&notrans,&ncol,&one,&nrow,&alpha,XXinvX,&ncol,Y,&nrow,
&beta,coef,&ncol);
printf("\n\nCoefficient Vector = ");
for(i=0;i<ncol;i++)

```

```
{
    printf("\n%d %12.6f", i, coef[i]);
}
printf("\n\n");
free(X);
free(Y);
free(XprimeX);
free(XXinvX);
free(coef);
free(ipiv);

fclose(fp);
return(0);
}
```

## ols\_read\_svd.c

```
/*
c:/mingw/bin/gcc -I"c:/program files/R/R-2.9.0/include" -L"C:/Program
Files/R/R-2.9.0/bin" -Wall %1.c -o %1.exe -lRlapack -lRblas

General OLS program.  Reads matrix created by writedata_ols.c

The only parameters the user has to set are the number of rows and
columns -- nrow and ncol below.  The number of columns counts a column
of "1"s used for the intercept term.  All memory is then dynamically
allocated using nrow and ncol.

This version does a Singular Value Decomposition on the input matrix
*/
#include <math.h>
#include <time.h>
#include <stdlib.h>
#include <stdio.h>
#include <string.h>
#include <R_ext/Lapack.h>
#include <R_ext/BLAS.h>

void xsvd(int kpnq, int kpnq, double *, double *, double *, double *);

FILE *fp;
FILE *jp;

int main(){

    int i, j, info, errno;
    char trans = 't', notrans = 'n';
    double alpha = 1.0, beta=0.0;
    int nrow=1000, ncol=25;
    int one=1;
    double *X, *Y, *XprimeX, *XXinv, *XXinvX, *coef;
    double *u, *lambda, *vt;
    int *ipiv;
    double time1, time2, timedif;

    X = (double *) malloc (nrow*ncol*sizeof(double));
    Y = (double *) malloc (nrow*sizeof(double));
    XprimeX = (double *) malloc (ncol*ncol*sizeof(double));
    XXinv = (double *) malloc (ncol*ncol*sizeof(double));
    XXinvX = (double *) malloc (nrow*ncol*sizeof(double));
    coef = (double *) malloc (ncol*sizeof(double));
    ipiv = (int *) malloc (ncol*sizeof(int));
    u = (double *) malloc (nrow*nrow*sizeof(double));
    lambda = (double *) malloc (ncol*ncol*sizeof(double));
    vt = (double *) malloc (ncol*ncol*sizeof(double));
/* clock() is part of time.h -- returns the implementation's
 * best approximation to the processor time elapsed since the
 * program was invoked, divide by CLOCKS_PER_SEC to get the time
 * in seconds */
    time1 = (double) clock(); /* get initial time */
```

```

time1 = time1 / CLOCKS_PER_SEC;          /*    in seconds    */

printf("\nnumber of rows = %d  number of columns = %d\n\n",nrow,ncol);

jp = fopen("c:/docs_c_summer_course/data_ols_svd.txt","w");

if((fp = fopen("c:/docs_c_summer_course/data_ols.txt","r"))==NULL)
{
    printf("\nUnable to open file OLS_DATA.TXT: %s\n",
strerror(errno));
    exit(EXIT_FAILURE);
}
else {

    fprintf(jp," Y and X = \n");
    for(i=0;i<nrow;i++)
    {
        fscanf(fp,"%lf",&Y[i]);
        for(j=0;j<ncol;j++)
        {
            fscanf(fp,"%lf",&X[i+j*nrow]);
        }
        fprintf(jp,"%10d %12.6f", i,Y[i]);
        for(j=0;j<ncol;j++)
        {
            fprintf(jp,"%12.6f",X[i+j*nrow]);
        }
        fprintf(jp,"\n");
    }
}

/* Call Singular Value Decomposition Routine to look at the colinearity
* in X */
/* Clock the SVD Routine*/

time2 = (double) clock();                /* get initial time */
time2 = time2 / CLOCKS_PER_SEC;          /*    in seconds    */
xsvd(nrow,ncol,X,u,lambda,vt);
timedif = ( ((double) clock()) / CLOCKS_PER_SEC) - time2;
printf("SVD took %12.8f seconds\n", timedif);
fprintf(jp,"SVD took %12.8f seconds\n", timedif);

dgemm_(&trans,&notrans,&ncol,&ncol,&nrow,&alpha,X,&nrow,X,&nrow,&beta,
XprimeX,&ncol);
fprintf(jp,"\n\nX'X = \n");
for(i=0;i<ncol;i++)
{
    for(j=0;j<ncol;j++)
    {
        fprintf(jp,"%12.6f",XprimeX[i+j*ncol]);
    }
    fprintf(jp,"\n");
}

/* Initialize the Identity matrix */
for(i=0;i<ncol;i++)
{

```

```

        for(j=0;j<ncol;j++)
        {
            XXinv[i+j*ncol]=0.0;
            if(i == j)XXinv[i+j*ncol]=1.0;
        }
    }
    dgesv_(&ncol,&ncol,XprimeX,&ncol,ipiv,XXinv,&ncol,&info);
    fprintf(jp,"\n\n(X'X)-1 = \n");
    for(i=0;i<ncol;i++)
    {
        for(j=0;j<ncol;j++)
        {
            fprintf(jp,"%12.6f",XXinv[i+j*ncol]);
        }
        fprintf(jp,"\n");
    }

//XXinv is 2x2
//X' is 2x5
//X is 5x2

        dgemm_(&notrans,&trans,&ncol,&nrow,&ncol,&alpha,XXinv,&ncol,X,&nrow,&beta,XXinvX,&ncol);

//XXinvX is 2x5
//Y is 5x1

        dgemm_(&notrans,&notrans,&ncol,&one,&nrow,&alpha,XXinvX,&ncol,Y,&nrow,&beta,coef,&ncol);
        printf(jp,"\n\nCoefficient Vector = ");
        printf("\n\nCoefficient Vector = ");
        for(i=0;i<ncol;i++)
        {
            printf("\n%d %12.6f", i, coef[i]);
            fprintf(jp,"\n%d %12.6f", i, coef[i]);
        }
        printf("\n\n");
        free(X);
        free(Y);
        free(XprimeX);
        free(XXinvX);
        free(coef);
        free(ipiv);
        free(u);
        free(lambda);
        free(vt);
        timedif = ( ((double) clock()) / CLOCKS_PER_SEC) - timel;
        printf("The total elapsed time of the program is %12.8f seconds\n",
timedif);
        fprintf(jp,"\n\nThe total elapsed time of the program is %12.8f
seconds\n", timedif);

        fclose(fp);
        fclose(jp);
        return(0);

```



```
}  
/*
```

### Singular Value Decomposition Subroutine

```
*/  
void xsvd(int kpnq, int kpnq, double *y, double *u, double *lambda, double  
*vt) {  
/*  
*/  
  
    double *a, *work;  
    double sumulv, svd_error_sum, svd_error_sum_2;  
    int i, j, jj;  
    int info = 12;  
    int lwork= kpnq*kpnq+kpnq*kpnq;  
    int lda,ldu,ldvt;  
  
    a      = calloc( kpnq*kpnq, sizeof(double));  
    work   = calloc( lwork, sizeof(double));  
  
    fprintf(jp,"entering svd...\n");  
  
    lda = kpnq;  
    ldu = kpnq;  
    ldvt = kpnq;  
    for (i=0;i<lwork;i++){  
        work[i] = 0;  
    }  
  
    fprintf(jp,"lwork=%i\n",lwork);  
  
    for (j=0;j<kpnq;j++) {  
        for (i=0;i<kpnq;i++) {  
            a[(j*kpnq)+i] = y[(j*kpnq)+i];  
        }  
    }  
  
    dgesvd_("A","A", &kpnq, &kpnq, a, &lda, lambda,  
           u, &ldu, vt, &ldvt, work, &lwork, &info);  
  
    fprintf(jp,"Info = %i\n",info);  
    printf("Info = %i\n",info);  
    fprintf(jp,"Singular Values\n");  
    printf("Singular Values\n");  
    for(jj=0;jj<kpnq;jj++)  
    {  
        fprintf(jp,"%d %f\n",jj,lambda[jj]);  
        printf("%d %f\n",jj,lambda[jj]);  
    }  
  
/*  
    Do simple check of SVD  
*/
```

```

svd_error_sum=0.0;
svd_error_sum_2=0.0;
for (i=0;i<kpnp;i++)
{
    for (jj=0;jj<kpnq;jj++)
    {
        sumulv=0.0;
        for (j=0;j<kpnq;j++)
        {
            sumulv+=u[(j*kpnp)+i]*lambda[j]*vt[j+(jj*kpnq)];
        }
        svd_error_sum+=(y[i+(jj*kpnp)]-sumulv)*(y[i+(jj*kpnp)]-
sumulv);
        svd_error_sum_2+=fabs(y[i+(jj*kpnp)]-sumulv);
    }
}
fprintf(jp,"SVD Error Check = %12.7g
%12.7g\n",svd_error_sum,svd_error_sum_2);
printf("SVD Error Check = %12.7g
%12.7g\n",svd_error_sum,svd_error_sum_2);
fprintf(jp,"Leaving svd...\n");
free(work);
free(a);
}

```

## Subroutine DGESVD from LAPACK Library

```

SUBROUTINE DGESVD( JOBU, JOBVT, M, N, A, LDA, S, U, LDU, VT, LDVT,
$                WORK, LWORK, INFO )
*
* -- LAPACK driver routine (version 3.2) --
* -- LAPACK is a software package provided by Univ. of Tennessee, --
* -- Univ. of California Berkeley, Univ. of Colorado Denver and NAG Ltd.--
*   November 2006
*
* .. Scalar Arguments ..
CHARACTER          JOBU, JOBVT
INTEGER           INFO, LDA, LDU, LDVT, LWORK, M, N
*
* ..
* .. Array Arguments ..
DOUBLE PRECISION  A( LDA, * ), S( * ), U( LDU, * ),
$                VT( LDVT, * ), WORK( * )
*
* ..
*
* Purpose
* =====
*
* DGESVD computes the singular value decomposition (SVD) of a real
* M-by-N matrix A, optionally computing the left and/or right singular
* vectors. The SVD is written
*
*       A = U * SIGMA * transpose(V)
*
* where SIGMA is an M-by-N matrix which is zero except for its
* min(m,n) diagonal elements, U is an M-by-M orthogonal matrix, and
* V is an N-by-N orthogonal matrix. The diagonal elements of SIGMA
* are the singular values of A; they are real and non-negative, and
* are returned in descending order. The first min(m,n) columns of
* U and V are the left and right singular vectors of A.
*
* Note that the routine returns V**T, not V.
*
* Arguments
* =====
*
* JOBU      (input) CHARACTER*1
*           Specifies options for computing all or part of the matrix U:
*           = 'A': all M columns of U are returned in array U;
*           = 'S': the first min(m,n) columns of U (the left singular
*                 vectors) are returned in the array U;
*           = 'O': the first min(m,n) columns of U (the left singular
*                 vectors) are overwritten on the array A;
*           = 'N': no columns of U (no left singular vectors) are
*                 computed.
*
* JOBVT     (input) CHARACTER*1
*           Specifies options for computing all or part of the matrix
*           V**T:
*           = 'A': all N rows of V**T are returned in the array VT;
*           = 'S': the first min(m,n) rows of V**T (the right singular

```

```

*          vectors) are returned in the array VT;
*    = 'O': the first min(m,n) rows of V**T (the right singular
*          vectors) are overwritten on the array A;
*    = 'N': no rows of V**T (no right singular vectors) are
*          computed.
*
*    JOBVT and JOBU cannot both be 'O'.
*
* M      (input) INTEGER
*        The number of rows of the input matrix A.  M >= 0.
*
* N      (input) INTEGER
*        The number of columns of the input matrix A.  N >= 0.
*
* A      (input/output) DOUBLE PRECISION array, dimension (LDA,N)
*        On entry, the M-by-N matrix A.
*        On exit,
*        if JOBU = 'O', A is overwritten with the first min(m,n)
*          columns of U (the left singular vectors,
*          stored columnwise);
*        if JOBVT = 'O', A is overwritten with the first min(m,n)
*          rows of V**T (the right singular vectors,
*          stored rowwise);
*        if JOBU .ne. 'O' and JOBVT .ne. 'O', the contents of A
*          are destroyed.
*
* LDA    (input) INTEGER
*        The leading dimension of the array A.  LDA >= max(1,M).
*
* S      (output) DOUBLE PRECISION array, dimension (min(M,N))
*        The singular values of A, sorted so that S(i) >= S(i+1).
*
* U      (output) DOUBLE PRECISION array, dimension (LDU,UCOL)
*        (LDU,M) if JOBU = 'A' or (LDU,min(M,N)) if JOBU = 'S'.
*        If JOBU = 'A', U contains the M-by-M orthogonal matrix U;
*        if JOBU = 'S', U contains the first min(m,n) columns of U
*        (the left singular vectors, stored columnwise);
*        if JOBU = 'N' or 'O', U is not referenced.
*
* LDU    (input) INTEGER
*        The leading dimension of the array U.  LDU >= 1; if
*        JOBU = 'S' or 'A', LDU >= M.
*
* VT     (output) DOUBLE PRECISION array, dimension (LDVT,N)
*        If JOBVT = 'A', VT contains the N-by-N orthogonal matrix
*        V**T;
*        if JOBVT = 'S', VT contains the first min(m,n) rows of
*        V**T (the right singular vectors, stored rowwise);
*        if JOBVT = 'N' or 'O', VT is not referenced.
*
* LDVT   (input) INTEGER
*        The leading dimension of the array VT.  LDVT >= 1; if
*        JOBVT = 'A', LDVT >= N; if JOBVT = 'S', LDVT >= min(M,N).
*

```

```

* WORK      (workspace/output) DOUBLE PRECISION array, dimension
(MAX(1,LWORK))
*          On exit, if INFO = 0, WORK(1) returns the optimal LWORK;
*          if INFO > 0, WORK(2:MIN(M,N)) contains the unconverged
*          superdiagonal elements of an upper bidiagonal matrix B
*          whose diagonal is in S (not necessarily sorted). B
*          satisfies  $A = U * B * VT$ , so it has the same singular values
*          as A, and singular vectors related by U and VT.
*
* LWORK     (input) INTEGER
*          The dimension of the array WORK.
*          LWORK >= MAX(1,3*MIN(M,N)+MAX(M,N),5*MIN(M,N)).
*          For good performance, LWORK should generally be larger.
*
*          If LWORK = -1, then a workspace query is assumed; the routine
*          only calculates the optimal size of the WORK array, returns
*          this value as the first entry of the WORK array, and no error
*          message related to LWORK is issued by XERBLA.
*
* INFO      (output) INTEGER
*          = 0: successful exit.
*          < 0: if INFO = -i, the i-th argument had an illegal value.
*          > 0: if DBDSQR did not converge, INFO specifies how many
*          superdiagonals of an intermediate bidiagonal form B
*          did not converge to zero. See the description of WORK
*          above for details.
*
* =====
*

```